

LECTURE 12

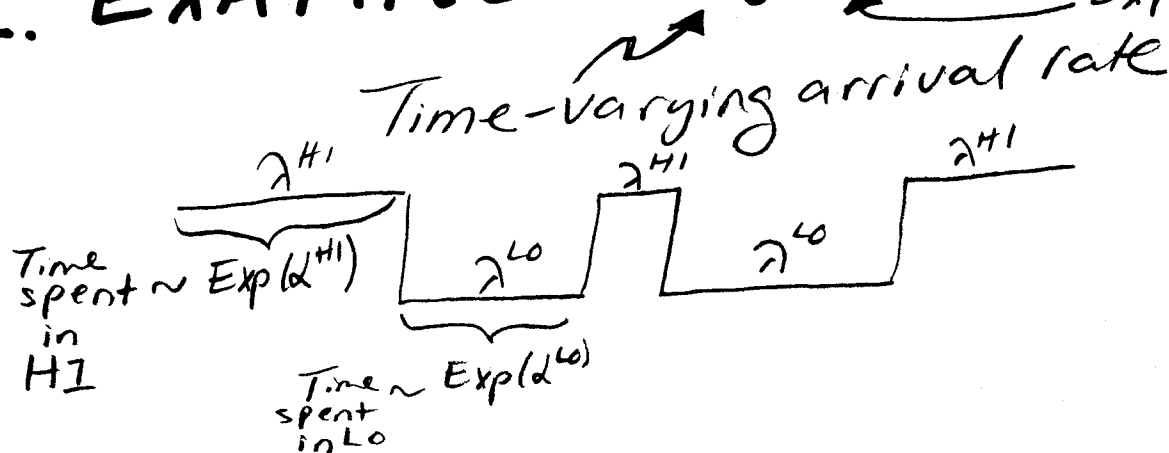
MATRIX-ANALYTIC METHODS

(a.k.a. Matrix-Geometric methods)

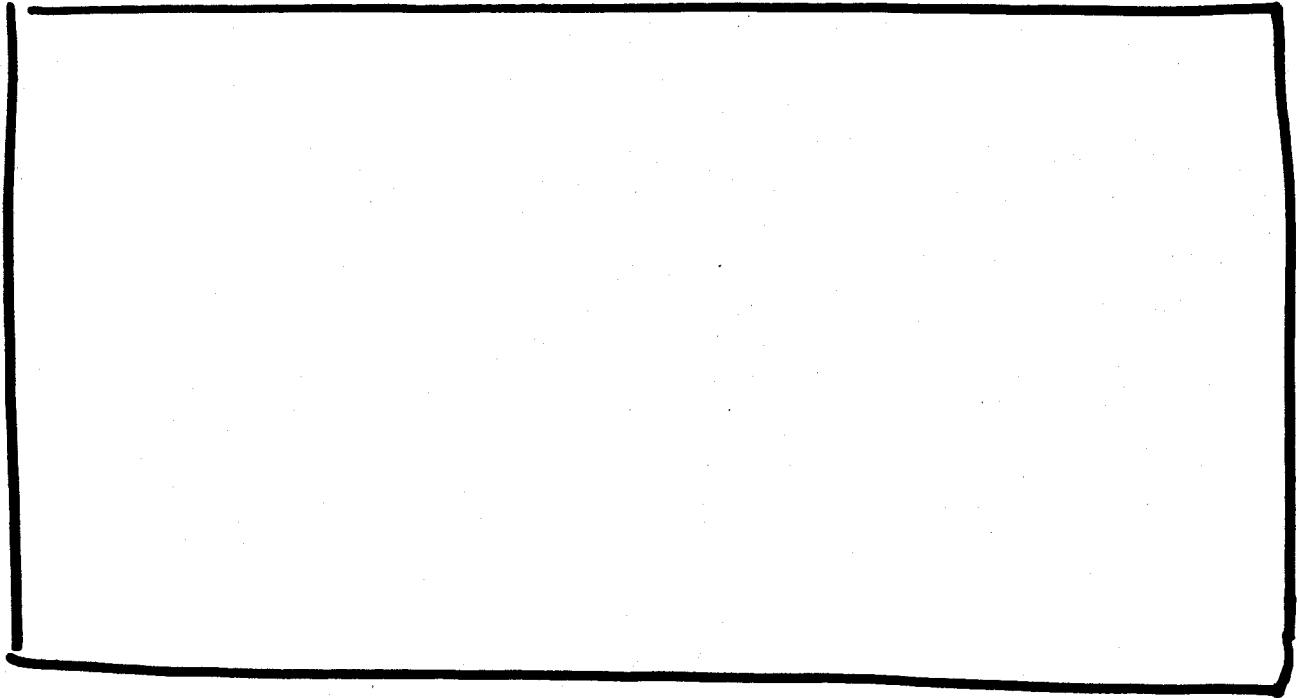
I. MOTIVATION

- Finite-state Markov Chains are easy to solve
- Infinite-state Markov Chains are easy too, if have 1 row ; repeat
e.g. M/M/1
- But what do you do when have > 1 row and infinite states?

II. EXAMPLE - $M_t/M/1$ $\text{Exp}(\mu)$

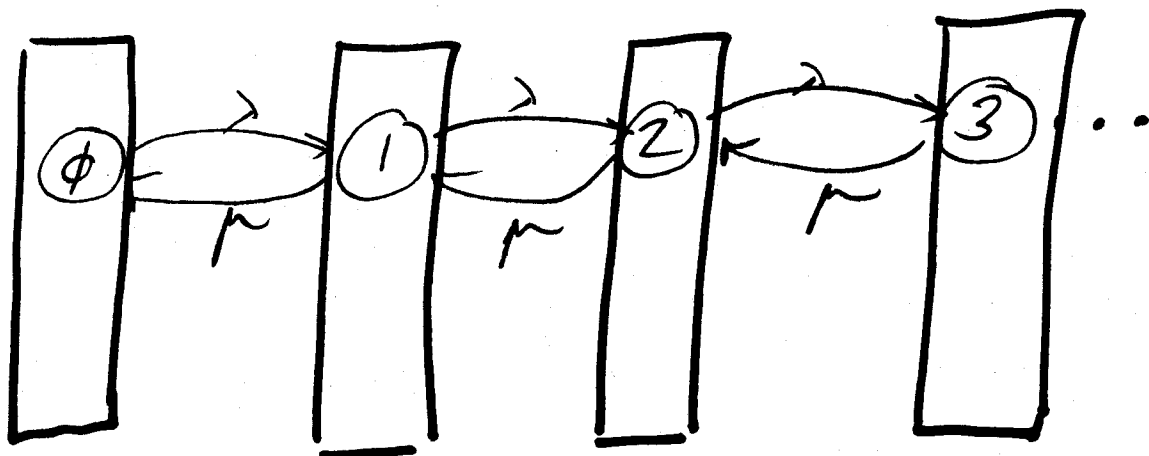


FILL IN CTMC REPRESENTING
 $M_t/M/1$ MODEL:



- NOTE:
- ① REPEATING STRUCTURE
 - ② CAN WE SOLVE RECURSIVELY LIKE IN $M/M/1$?

III. BACK TO $M/M/1$.

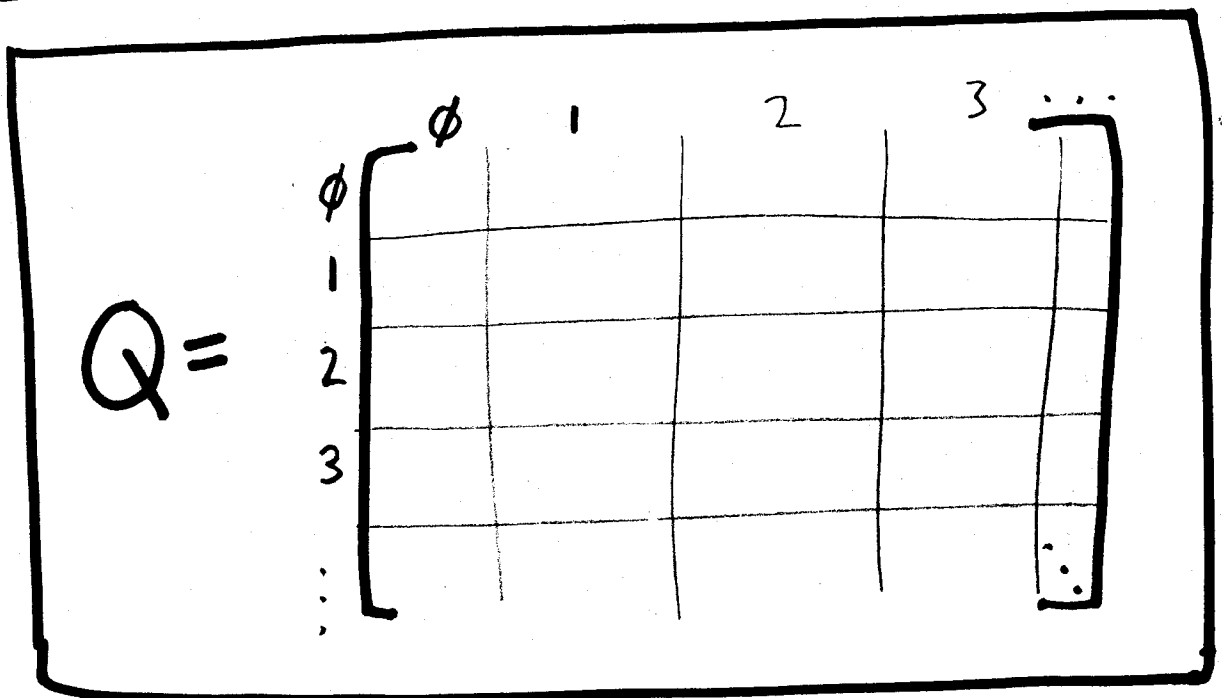


②

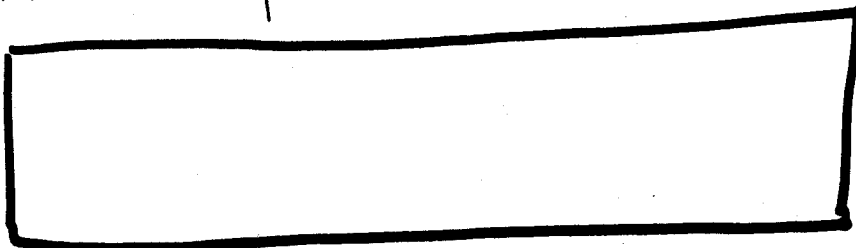
• Write balance eqns in this form

$$\begin{matrix} \overrightarrow{\Pi} \\ (\pi_0, \pi_1, \pi_2, \dots) \end{matrix} \cdot \begin{matrix} \text{Q} \\ \uparrow \\ \text{"GENERATOR MATRIX"} \end{matrix} = \overrightarrow{\phi}$$

What is Q?



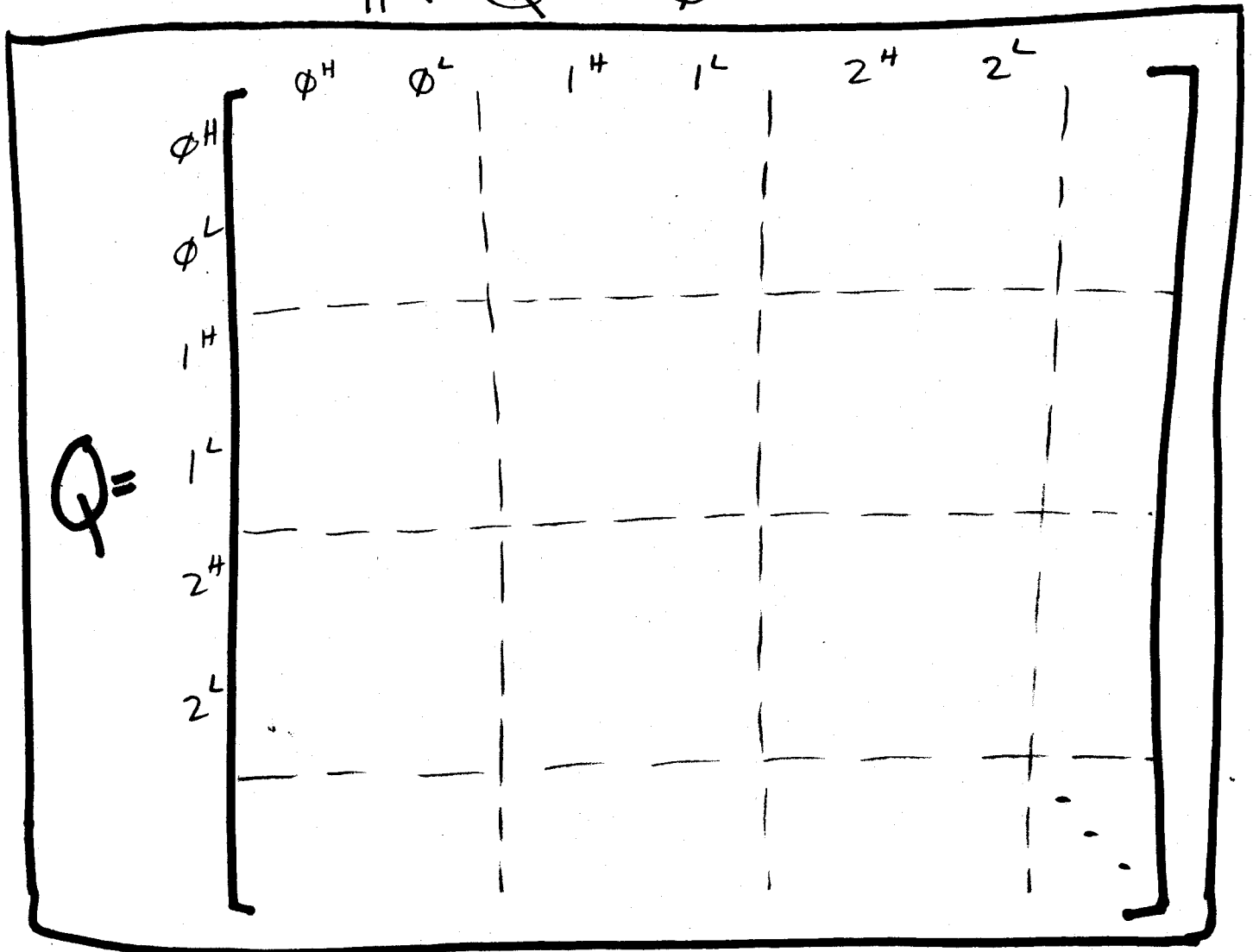
We also need normalization eqn:
Write as product of 2 vectors:



IV \mathcal{Q} AND ITS SUBMATRICES

What is \mathcal{Q} for the $M_t/M/1$?

$$\vec{\pi} \cdot \mathcal{Q} = \vec{\Phi}$$



Notation: $\vec{\pi}_j = (\pi_j^H, \pi_j^L)$

Backward

$$\vec{B} = [\quad]$$

Local

$$\vec{L} = [\quad]$$

Forward

$$\vec{F} = [\quad]$$

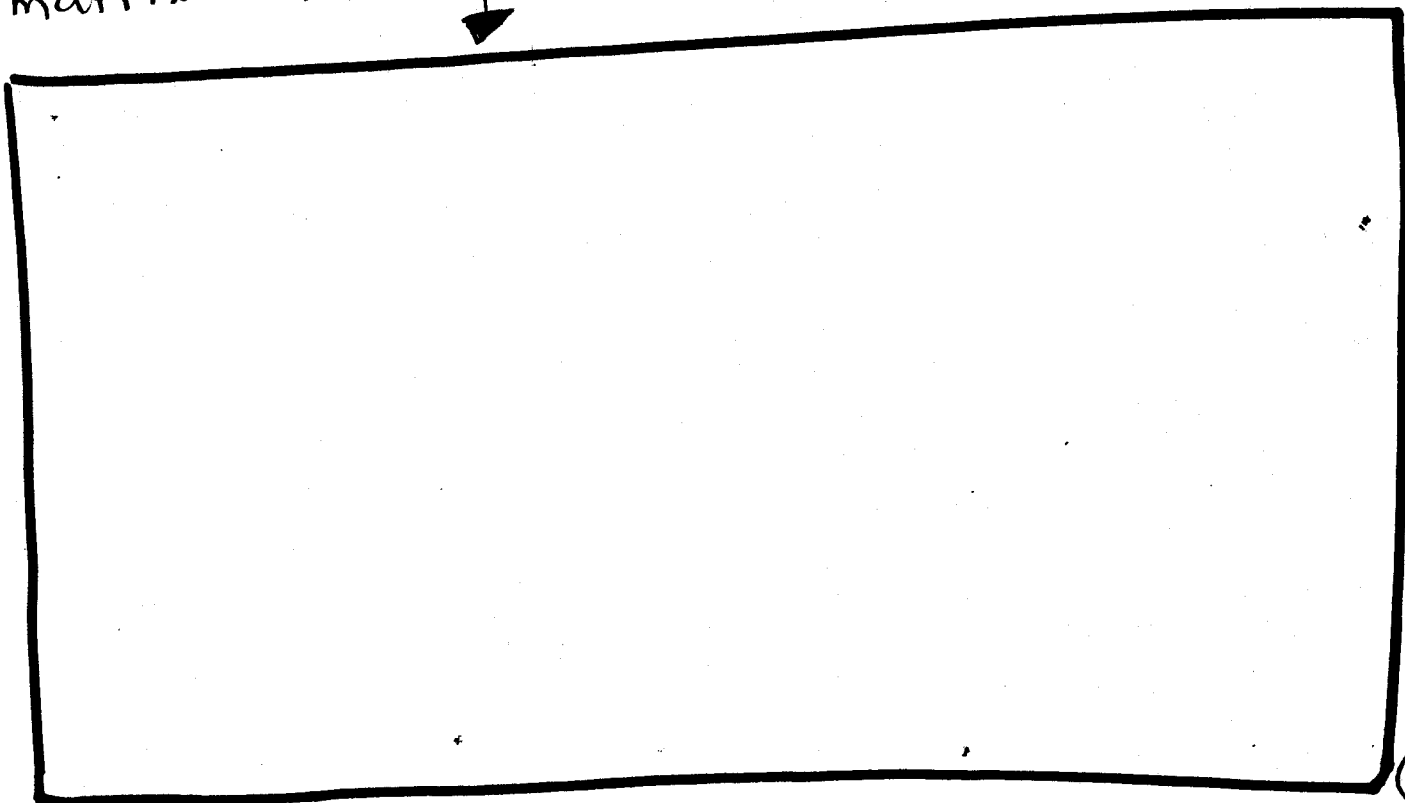
$L_0 = [\quad] =$ Local transitions for initial part

$Q =$

	ϕ^H	ϕ^L	1^H	1^L	2^H	2^L	...
ϕ^H							
ϕ^L							
1^H							
1^L							
2^H							
2^L							
...							

Fill in matrix names

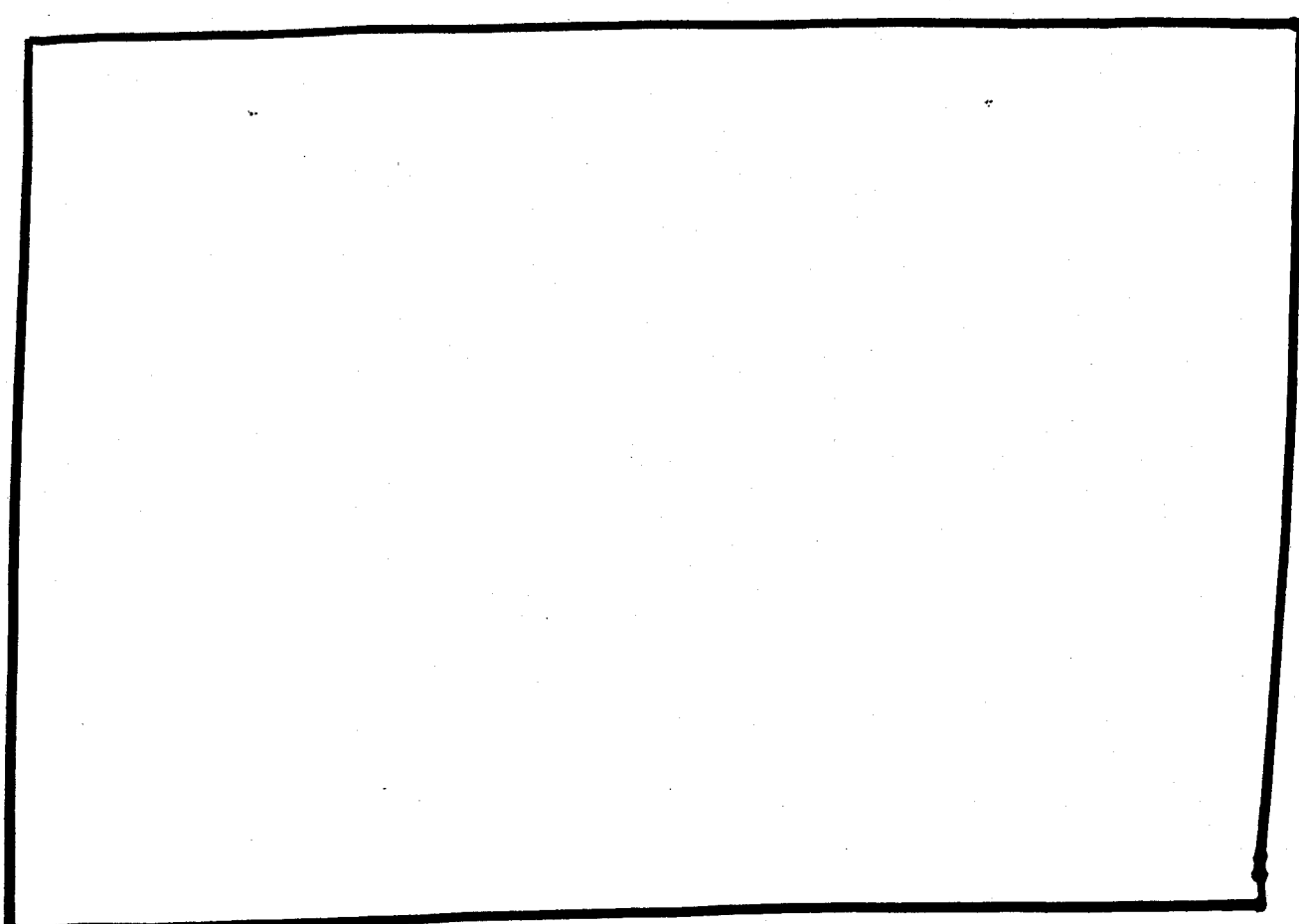
Rewrite balance eqns: $\vec{\pi} \cdot Q = \vec{\phi}$ as matrix eqns.



V. SOLVING FOR LIMITING PROBABILITIES

GUESS: $\vec{\pi}_i = \vec{\pi}_\phi \cdot R^i$
//
(π_i^H, π_i^L)

Substitute above "guess" into balance eqns:



Common Portion: $\Rightarrow F + RL + R^2B = \phi$

To get R

$$F + RL + R^2B = \phi$$

$$\Rightarrow RL = -(R^2B + F)$$


$$\Rightarrow R = -(R^2B + F)L^{-1}$$

Solve for R BY ITERATING:

$$R(\phi) = \mathbf{0} \quad \left. \vphantom{R(\phi)} \right\} \leftarrow \begin{array}{l} \text{matrix of} \\ \text{appropriate} \\ \text{dimension} \end{array}$$

While $\|R^{(n+1)} - R^{(n)}\| > \varepsilon$,

$$R^{(n+1)} = -(R^{(n)2}B + F)L^{-1}$$

 Keep iterating until get R

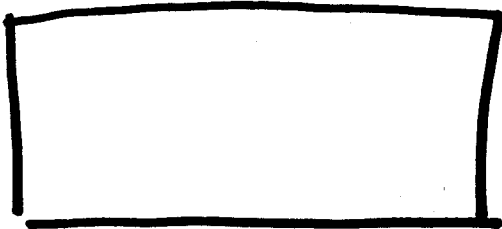
now: $\vec{\pi}_i = \vec{\pi}_\phi \cdot R^i$

satisfies balance eqns.

(7)

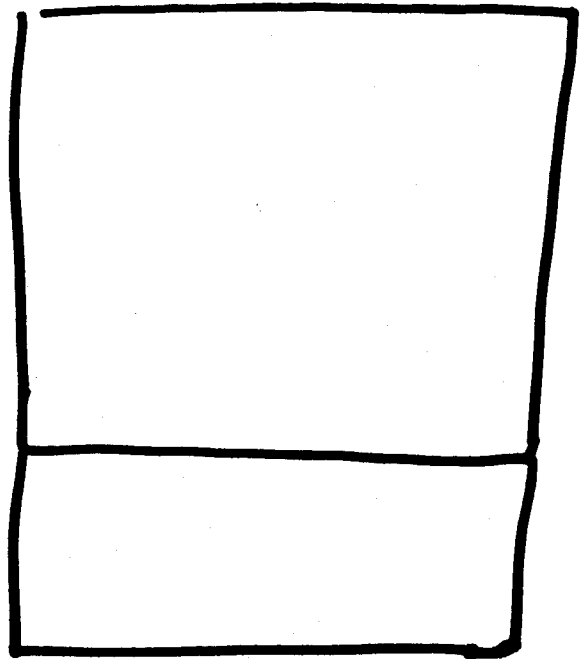
To get $\vec{\pi}_\phi = (\pi_\phi^{HI}, \pi_\phi^{LO})$

Fill in
first
Matrix Balance
Eqn
involving $\vec{\pi}_\phi$



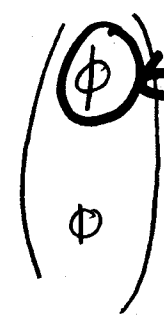
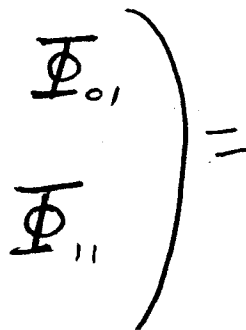
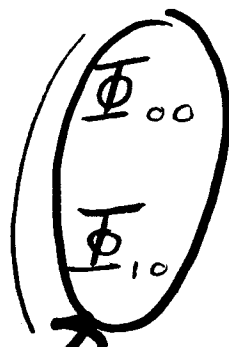
Rewrite
normalizing eqn

$\vec{\pi} \cdot \vec{e} = 1$
in terms of R and $\vec{\pi}_\phi$



Let $\Phi = L_\phi + RB$

$(\pi_\phi^{HI}, \pi_\phi^{LO})$



REPLACE
WITH:



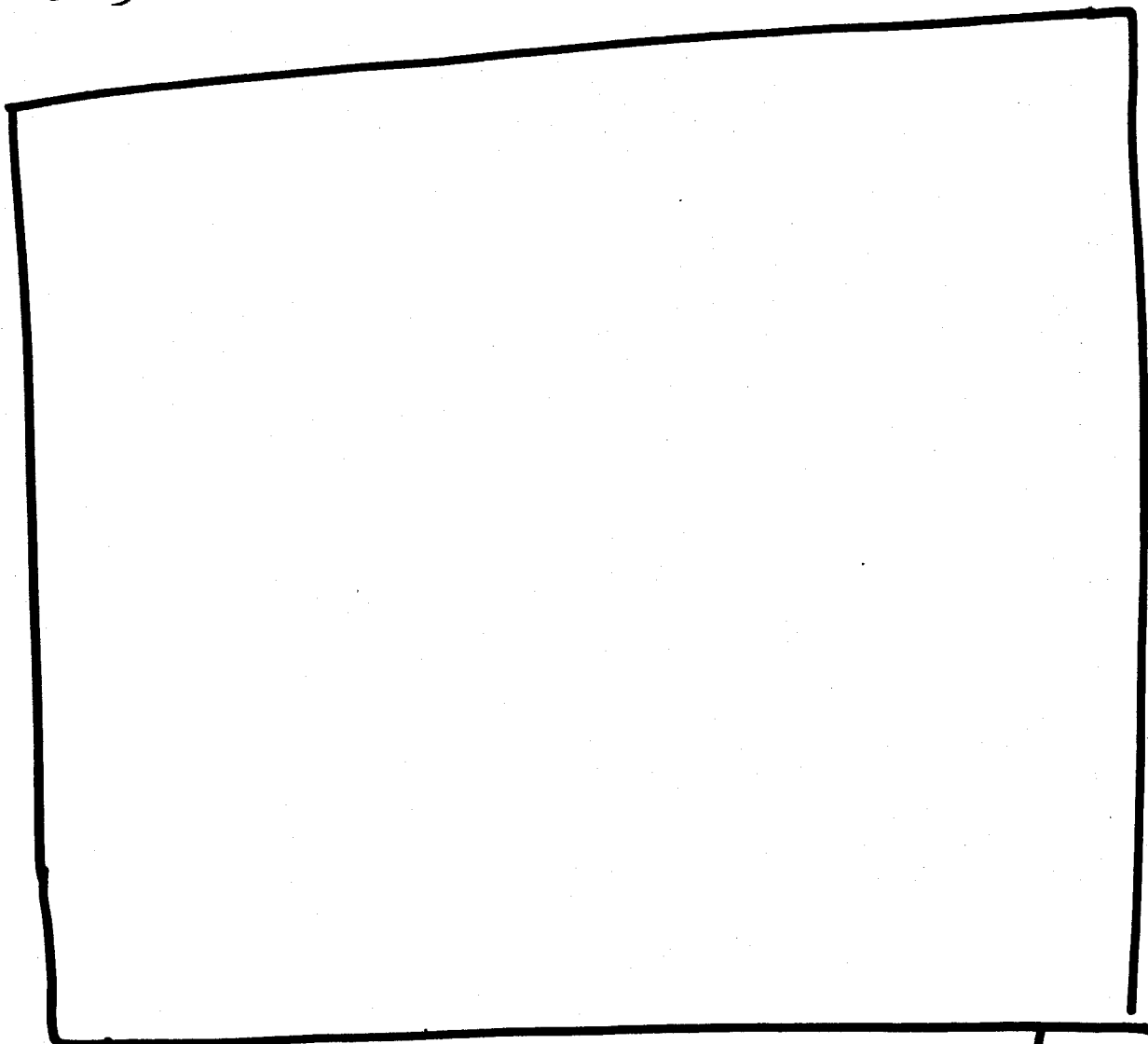
REPLACE
WITH:



SOLVE ABOVE
FOR $\vec{\pi}_\phi = (\pi_\phi^{HI}, \pi_\phi^{LO})$. (8)

VI. PERFORMANCE METRICS

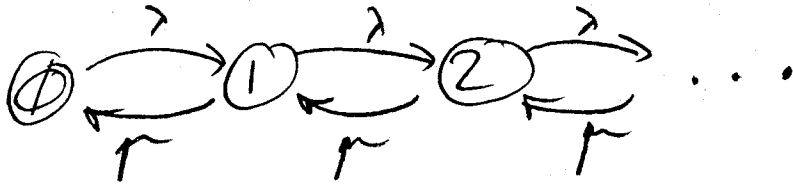
Derive closed-form expression for $E[N_s]$ in terms of only $\vec{\pi}_q$ and R :



$$E[N_s] =$$

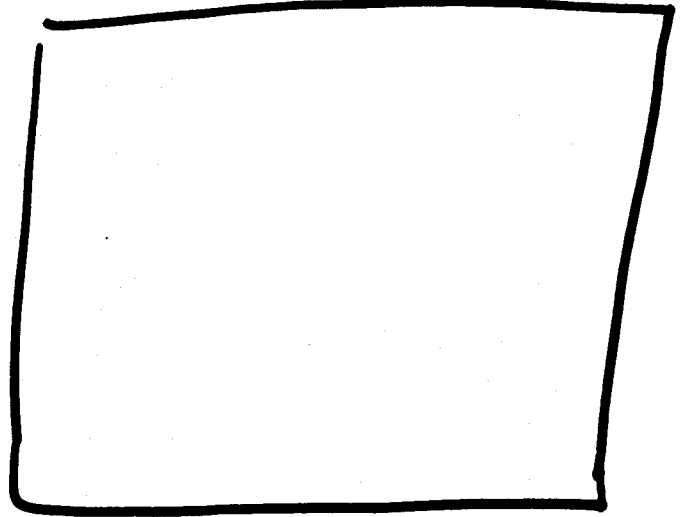
$$E[T_s] =$$

VII Back to M/M/1



$$\vec{\pi} \cdot Q = \vec{0}$$

$$Q =$$



$$B = \square$$

$$L = \square$$

$$F = \square$$

$$L_0 = \square$$

GUESS : $\pi_i = \pi_0 \cdot R^i$

From BAL EQNS : $F + RL + R^2B = 0$

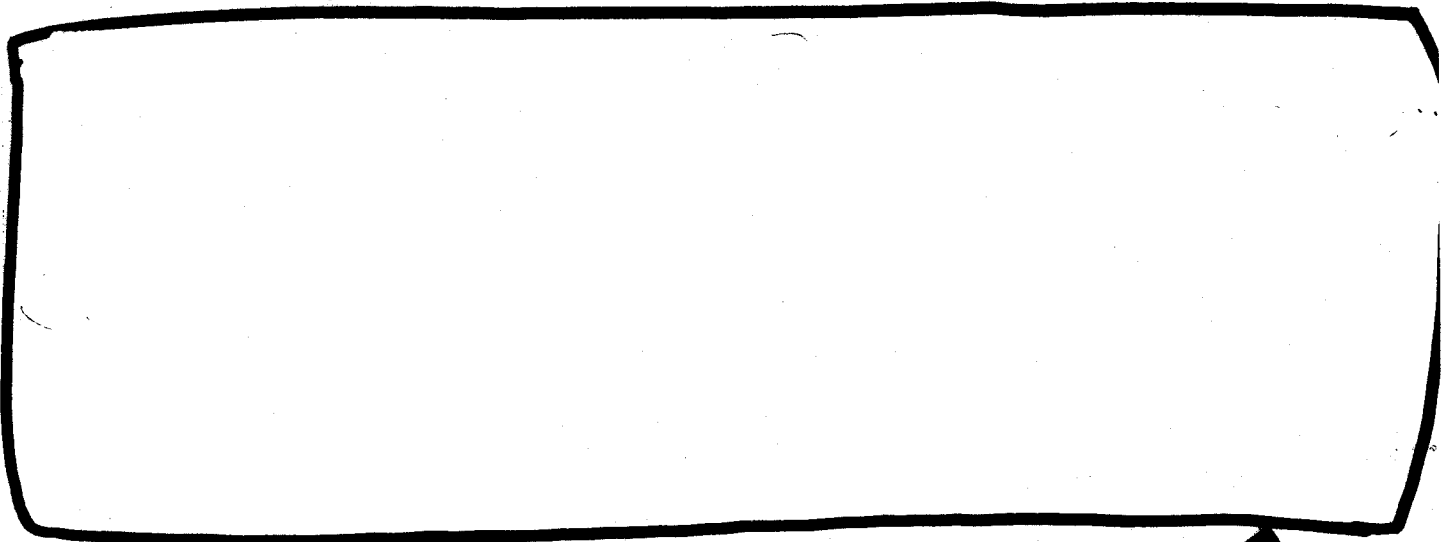
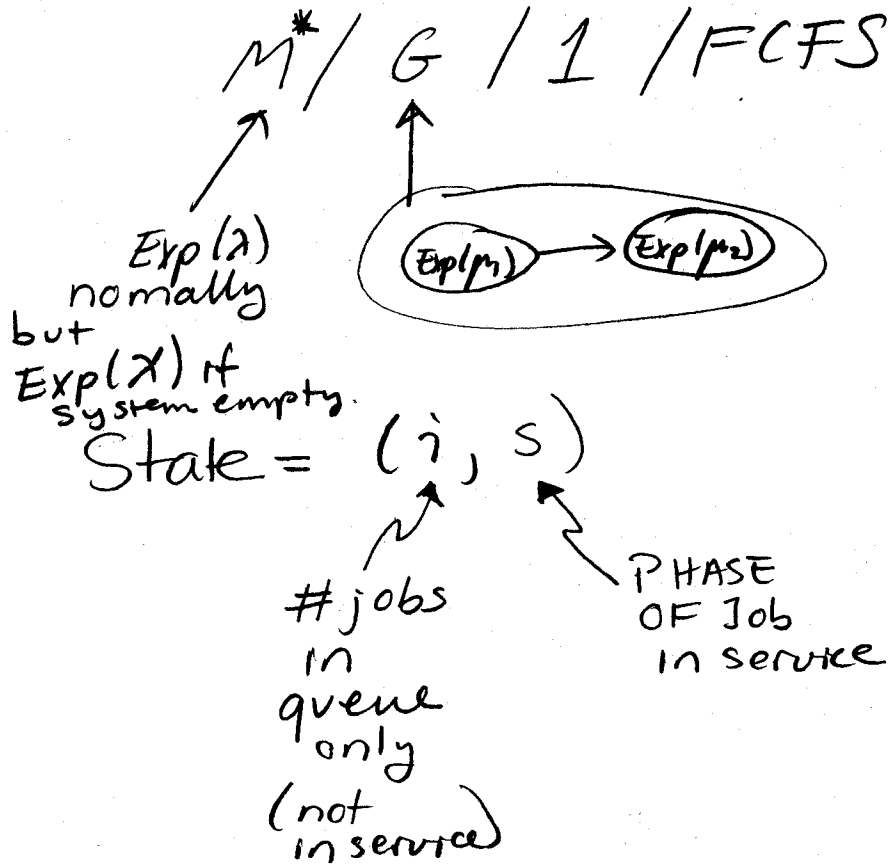
WHAT DOES THIS SAY ABOUT R?



$$\vec{\pi} \cdot \vec{e} = 1 \Rightarrow \pi_0 =$$

VIII MORE COMPLEX CHAINS

Sometimes repeating portion only starts after Level M.



DRAW THE MARKOV CHAIN: →

$Q =$

	(ϕ, ϕ)	$(\phi, 1)$	$(\phi, 2)$	$(1, 1)$	$(1, 2)$	$(2, 1)$	$(2, 2)$	$(3, 1)$	$(3, 2)$
(ϕ, ϕ)									
$(\phi, 1)$									
$(\phi, 2)$									
$(1, 1)$									
$(1, 2)$									
$(2, 1)$									
$(2, 2)$									
$(3, 1)$									
$(3, 2)$									

where $a_1 = \lambda + \mu_1$

$a_2 = \lambda + \mu_2$

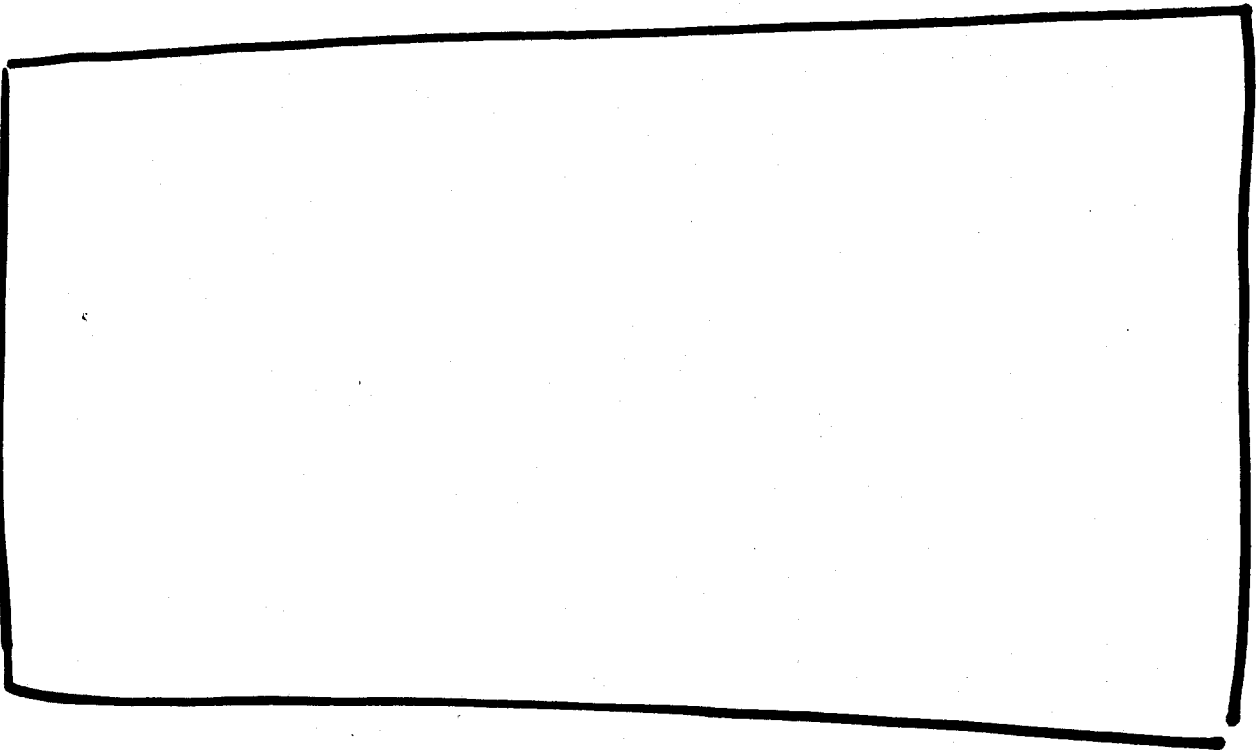
$Q =$

	<u>3</u>	<u>2</u>	<u>2</u>	<u>2</u>
3	L_ϕ	F_ϕ		
2	B_ϕ	L	F	
2		B	L	F
2			B	L

$$\vec{\pi}_\phi = (\pi_{(\phi,\phi)}, \pi_{(\phi,1)}, \pi_{(\phi,2)})$$

$$\vec{\pi}_\gamma = (\pi_{(\gamma,1)}, \pi_{(\gamma,2)})$$

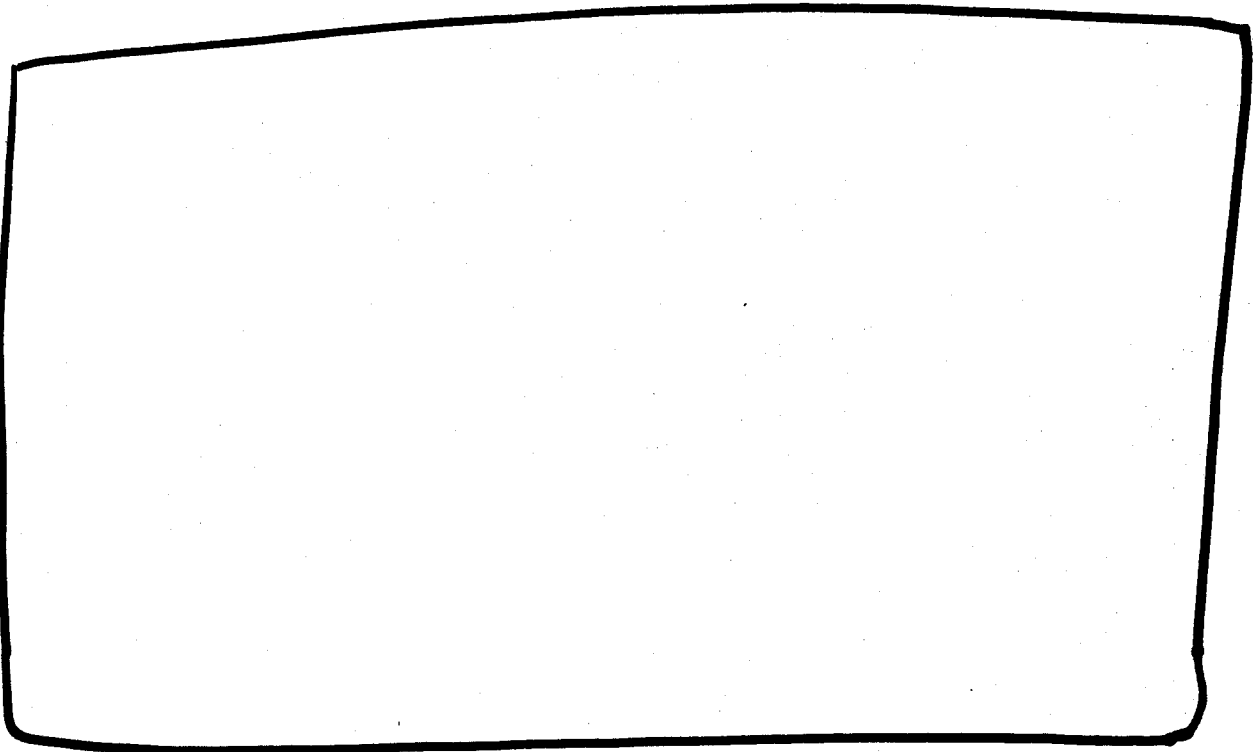
Balance Eqns



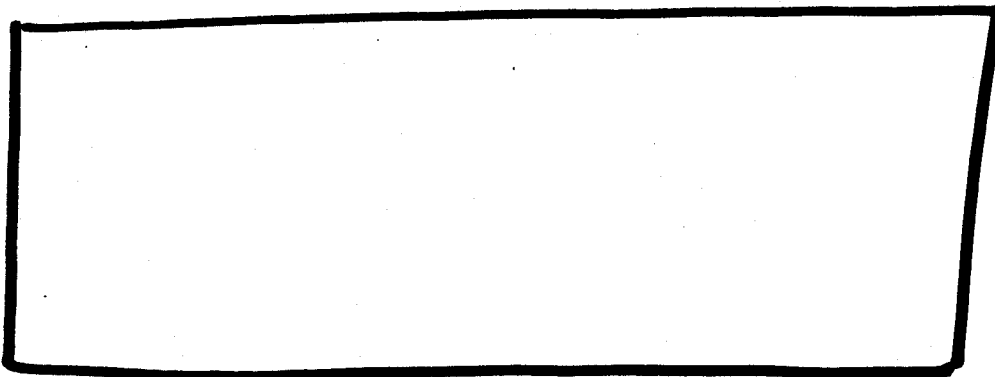
GUESS: $\vec{\pi}_{m+k} = \vec{\pi}_m \cdot R^k$

In this problem, $\vec{\pi}_m = \vec{\pi} \square$.

Balance Eqns incorporating
guess:



To determine R , iterate
over common portion:

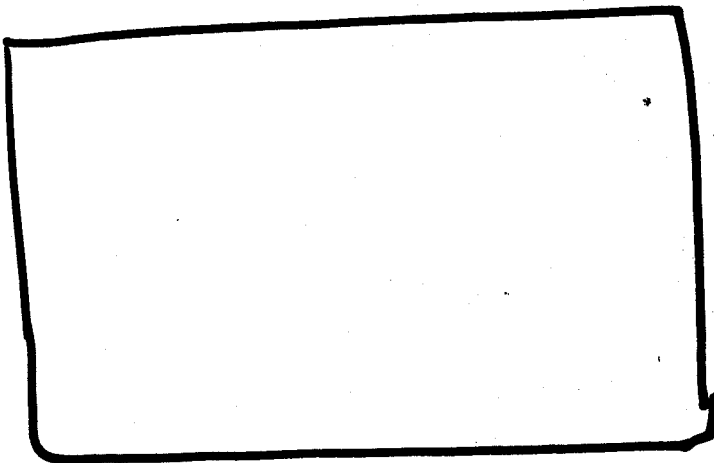


To determine initial portion:

$$\left(\begin{array}{c} \vec{\pi}_\phi \\ \vec{\pi}_1 \end{array} \right) \begin{bmatrix} L_\phi & F_\phi \\ B_\phi & L+RB \end{bmatrix} = (\phi, \phi, \phi, \phi, \phi)$$

↑
replace
by

Replace
1st column by:



Homework: Practice with Matrix Analytic Method

Use the matrix analytic method from lecture to analyze the M/PH/1 queue. The arrival process is Poisson(λ). The service time distribution is *phase-type* with 2 stages. Specifically, the service time distribution may be described as follows:

Start with an Exponential(μ_1). After that, with probability $1-p$, do nothing, but with probability p , add on another Exponential(μ_2).

To make this concrete, I will ask you to solve the problem for the case where $\lambda = 1$, $\mu_1 = 2$, $\mu_2 = 3$, and $p = .4$. I highly recommend using Matlab to solve this problem!

Here are some steps to help you:

1. Define a state space.
2. Draw out the Markov Chain.
3. Write out the generator matrix Q (it's infinite, so a portion will do).
4. Write out the matrices denoted by: L_0, F_0, B_0, F, L, B . [Check: L should be a 2x2 matrix].
5. Write out the balance equations and make the appropriate guess for the repeating part of the limiting probabilities.
6. Solve for the matrix R . [Check: R should be a 2x2 matrix].
7. Use the initial (non-repeating) balance equations together with the normalization constraint to solve for the initial limiting probabilities. Remember that these may be vectors. [Check: Compute the probability of there being zero jobs in the system. This should equal $1 - \rho$. [Hint: When I did this, I found that the probability that there are zero jobs in the system was: .3669 The total probability that there is one job in the system is: .2446]
8. At this point you should have all the limiting probabilities. Use these to compute $E[N_S]$ and $E[T_S]$.
9. Check your answer by applying the P-K formula for the M/G/1 queue.